

Quantum choice models: a flexible new approach for understanding moral decision-making

Thomas O. Hancock (Corresponding Author)

Choice Modelling Centre and Institute for Transport Studies
University of Leeds
T.O.Hancock@leeds.ac.uk

Jan Broekaert

Choice Modelling Centre and Institute for Transport Studies
University of Leeds
jan.b.broekaert@gmail.com

Stephane Hess

Choice Modelling Centre and Institute for Transport Studies
University of Leeds
S.Hess@leeds.ac.uk

Charisma F. Choudhury

Choice Modelling Centre and Institute for Transport Studies
University of Leeds
C.F.Choudhury@leeds.ac.uk

1 ABSTRACT

2 Quantum probability, first developed in theoretical physics, has recently been successfully used in
3 cognitive psychology to model data from experiments that previously resisted effective modelling
4 by classical methods. This has led to the development of choice models based on quantum
5 probability, which have greater flexibility than standard models due to the implementation of
6 complex numbers through, for example, complex phases or ‘quantum rotations’. This paper
7 tests whether these new models can also capture choice modification under *implicit* ‘changing
8 perspectives’ in choice contexts with salient moral attributes. We apply these models to two
9 distinctly different case-studies. In the first, respondents have to make choices between route
10 alternatives with variable ‘concrete’ and ‘moral’ attributes - [Chorus et al. \(2018\)](#)’s ‘taboo trade-off’
11 between time-cost and deaths-injuries. The second study investigates how an individual weighs
12 wages and commuting times for themselves relative to the wages and commuting times for their
13 partner. Under both scenarios, we find that the flexibility provided by quantum choice models
14 allows them to accurately capture and formally explain choices across the differing contexts.

15

16 **Keywords:** Quantum probability; moral choice; travel behaviour

17 1. INTRODUCTION

18 Moral choice scenarios can be summarised as those where the choices or actions a decision-
19 maker takes could negatively impact other individuals. Thus, to the decision-maker, the choice
20 alternatives may to some extent be categorised as ‘right’ or ‘wrong’, depending on how serious
21 (and possibly how likely) the consequences are. As a result, the associated choices can perhaps be
22 more complex as they do not involve straightforward trade-offs between rather concrete attributes
23 of alternatives. For example, a decision-maker may not choose what they would choose based on
24 more attractive concrete features as they believe it to be an overall morally contentious option.
25 Alternatively, a set of alternatives may all have negative features, where different schools of moral
26 thought suggest different actions should be taken (for example, [Awad et al. \(2020\)](#) discuss country-
27 level variations in decision-making in ‘moral machine’ choice tasks).

28 While moral choice behaviour has received much attention in economics and psychology, it is
29 rarely considered in the choice modelling literature (see [Chorus 2015](#) for a detailed discussion).
30 This is despite the fact that many typical experiments conducted to understand or interpret an
31 individual’s preferences in moral choice scenarios use paradigms such as variations of the well-
32 known trolley problem (where a ‘runaway trolley’ has two possible paths, both of which will
33 result in the death of some individual(s), and the decision-maker must choose who to save), for
34 which a precise understanding of the trade-offs that are being made could be obtained using
35 choice models. This is perhaps due to the fact that an individual’s moral preferences are difficult
36 to investigate outside of the laboratory, with typical experimental methods for examining moral
37 choice scenarios often suffering from low external validity ([Bauman et al., 2014](#)). However, more
38 recently, moral choice behaviour has become more prominent in the travel behaviour modelling
39 community through, for example, the reinvention of the trolley problem as a self-driving car
40 problem ([Awad et al., 2018](#)). Thus far, there has not been much consideration given to the types
41 of choice models used for the modelling of such scenarios, despite the wide range of theoretical
42 explanations for moral behaviour that have been proposed ([Chorus, 2015](#)). However, some steps
43 towards the development of choice models specifically for moral choice contexts have been made
44 ([Chorus et al., 2018](#)).

45 In this paper, we specifically look at models based on quantum probability theory. These have
46 not yet been applied to moral choice scenarios, despite the adoption of such methods ‘allowing
47 for a re-examination of the challenge of formalising psychological concepts of conflict, ambiguity,
48 and uncertainty’ (Wang et al., 2013). Quantum probability theory has recently made a significant
49 impact in cognitive psychology (Bruza et al., 2015). This impact is in part due to the underlying
50 logic of quantum probability theory which revealed a fundamental lack of distributivity of propositions
51 concerning non-compatible features of an observed system (Birkhoff and Von Neumann, 1936).
52 This key difference between classical and quantum logic reveals that under quantum theory, the
53 law of probability following the distributivity of ‘and’ and ‘or’ of propositions – $A \wedge (B \vee C) = (A \wedge$
54 $B) \vee (A \wedge C)$ – may fail to hold (for a detailed example, see Hancock et al. 2020). Another essential
55 difference follows from the description of a system by using state vectors with complex-valued
56 components which entail the occurrence of interference effects when such states are superposed,
57 famously leading to the paradoxical state of Schrödinger’s cat being both dead and alive at the same
58 time in a historical thought experiment devised to point out the consequences of the entanglement
59 of the quantum system and its observer (Schrödinger, 1935). In effect, the measurement of a
60 property of a system occurs differently, namely by applying projection operators on the state vector
61 of a system which inherently ‘changes the system by making an observation’ - as opposed to simply
62 reading of the value of a pre-existent property of the system. Crucially, these features imply that the
63 adoption of quantum probability theory allows for a powerful and elegant framework for modelling
64 and understanding many ‘paradoxical’ findings which become ‘intuitive’ (Wang et al., 2013), such
65 as probability judgement errors (Busemeyer et al., 2011), question ordering effects (Trueblood
66 and Busemeyer, 2011) and violations of the ‘sure thing principle’ (Pothos and Busemeyer, 2009;
67 Broekaert et al., 2020). A classic example of a probability judgement error is given by Tversky
68 and Kahneman (1983), who found that participants, after reading ‘Linda was a philosophy major.
69 She is bright and concerned with issues of discrimination and social justice’, were more likely to
70 agree with the statement ‘Linda is a feminist bank teller’ than the statement ‘Linda is a bank teller’.
71 This subjective assessment clearly contradicts logical set theory in which the category “feminist
72 bank teller” is a subset of the category “bank teller”, and hence on probabilistic grounds of set
73 membership, this should lead to a lower association of Linda with the former category.

74 With, for example, ordering effects also frequently observed in choice modelling applications,
75 it is unsurprising that quantum models have also since made the transition into choice modelling
76 (Lipovetsky, 2018). Furthermore, quantum models can be used to accurately capture the ‘change of
77 decision context and mental state’ when moving between choices made under revealed preference
78 and stated preference settings (Yu and Jayakrishnan, 2018). Additionally, it has been demonstrated
79 that quantum probability theory can be implemented into choice models to accurately understand
80 route choice problems as well as best-worst choice behaviour in the context of alternative routes
81 (Hancock et al., 2020). Thus there appears to be ample scope for further developments of quantum
82 choice models, with our previous development of the notion of a ‘quantum rotation’ within a
83 choice model providing useful transitions across choice contexts. The aim of this paper is to build
84 on work presented in Hancock et al. (2020), which focussed solely on typical travel behaviour
85 data, by testing these models on more complex choice scenarios. We specifically test whether
86 these rotations and other quantum choice model features can equivalently be used to accurately
87 capture changes in choice context within moral choice scenarios.¹

¹A prior version of a formal model using rotations in choice scenarios with moral trade-off was developed by

88 We apply the models to two very different datasets. The first allows us to test whether quantum
89 rotations can be used to capture the impact of the presence of a ‘taboo trade-off’ (Chorus et al.,
90 2018) involving trade-offs between ‘moral’ and ‘concrete’ features.² The moral attributes of the
91 route alternatives appeal to the personal sense of *right* versus *wrong* grounded in the choice maker’s
92 socio-cultural and philosophical or religious association - like the personal answerability or blame
93 for opting for a route alternative with a higher expected number of deaths or severely injured
94 travellers. The concrete attributes on the other hand call for a more pragmatic material utility
95 which a priori does not ponder rightness or wrongness of the choice - like for instance the additional
96 time on a route alternative. It goes without saying that these categories may well be perceived as
97 intertwined; a faster route alternative with implicit detrimental environmental effects can appeal
98 to the choice maker’s ethical principles. Vice versa, a utilitarian based ethical approach held by a
99 choice maker could result in equating moral attributes with pragmatic features of the alternative.

100 The second data set tests whether quantum rotations can be used to capture differences between
101 how an individual weighs wage and commuting times for themselves relative to considering the
102 wages and commuting times for both their partner and themselves, developed by Swardh and
103 Algers (2009), with descriptions also in Beck and Hess (2016). An aspect of morality is again
104 appealed to in this experimental paradigm. The consideration of the partner’s situation may appeal
105 to the choice maker’s empathy or selfishness with respect to the partner, or, a particular balanced
106 choice may result from an evaluation of the pragmatic joint utility for the couple.

107 The remainder of this paper is organised as follows. Section 2 gives an introduction to quantum
108 probability, discusses how it has provided useful explanations for choices with a moral component
109 in cognitive psychology, and shows how we mathematically build our quantum choice models.
110 Section 3 shows the empirical application to our two moral choice datasets. We finish with some
111 conclusions and directions for future research.

112 2. THE QUANTUM PROBABILITY APPROACH

113 In this section, we first give a basic overview of the quantum probability approach; we refer
114 the reader to Busemeyer and Bruza (2012); Khrennikov (2010); Yearsley (2017); Yearsley and
115 Busemeyer (2016); Broekaert et al. (2016) for a more extensive coverage on the application of
116 quantum theory in decision-making. Next, we in turn look at how quantum probability can
117 be used to capture a change in perspective, and how it has been used to explain a number of
118 ‘paradoxical’ phenomena in cognitive psychology, some of which have moral components. Finally,
119 we demonstrate how we mathematically operationalise the quantum probability approach into the
120 models utilised in this paper.

121 2.1. Basic features of the approach

122 Under quantum models, each choice scenario is represented in a n -dimensional ‘Hilbert’ space,
123 which is spanned by a set of n orthonormal (possibly complex) vectors, with one vector for each
124 possible choice alternative. In essence, the cognitive process corresponding to the experimental
125 paradigm is implemented by performing operations on specifically constructed vectors of the

Hancock (2019).

²The authors Chorus et al. (2018) have coined the types of attributes as ‘sacred’ and ‘secular’. We have opted to denominate the attributes by more culturally neutral terms in comparison to Chorus et al. (2018).

126 Hilbert space.³ This vector represents the decision-maker’s behavioural belief-action state at a
 127 given moment in the experimental paradigm, in particular for the present datasets, expressing their
 128 preferences.

129 A basic example of this is given in Fig. (1), where we adapt the Hilbert space to the paradigm
 130 corresponding to the first dataset (Chorus et al., 2018). A similar example is described in more
 131 detail in the introduction of Hancock et al. (2020), where an individual is choosing whether to
 132 commute to work by car or by train.

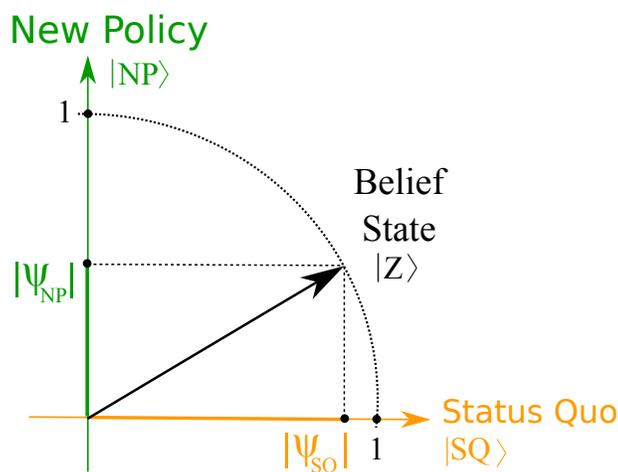


FIGURE 1 : A schematic representation of the belief state in the geometric quantum-like model for a binary choice between the ‘New Policy’ or the ‘Status Quo’. The belief state $|Z\rangle$ is a superposition of $|NP\rangle$ and $|SQ\rangle$, meaning that the decision-maker has a propensity to choose both the ‘New Policy’ or their ‘Status Quo’. The numerical probabilities of choosing each alternative are obtained from the complex-valued amplitudes of the projections on the respective axes by squaring the moduli $|\psi_{NP}|$ and $|\psi_{SQ}|$.

133 The preference of an individual decision-maker is represented by a (normalised) belief state
 134 vector which is denoted $|Z\rangle$. The action of making a choice is represented by a projection from
 135 the belief state vector onto the vector representing the chosen alternative, i.e. $|NP\rangle$ for the ‘New
 136 Policy’ or $|SQ\rangle$ for the ‘Status Quo’, in Fig. (1).

137 The projection operations are represented by the dotted lines connecting the belief state (on the
 138 arc) to the axes orthogonally spanned by the two choice alternatives, resulting in the two respective
 139 component moduli $|\psi_{NP}|$ and $|\psi_{SQ}|$. To be used as probabilities, the outputs of these projection
 140 processes need to fulfil two properties; a) they need to all be between 0 and 1, and b) they need
 141 to sum to 1. With the quantum approach, this is achieved by using the *squared* ‘length’ of each
 142 projection as the probability for that alternative. Since the state vector is normalised - i.e. of unit
 143 ‘length’ (or modulus) - these two requirements are fulfilled. One can easily verify that with the
 144 two choices represented by a set of orthonormal vectors, the set of squared ‘length’ projections
 145 will sum to one according Pythagoras’ Theorem (see Fig. 1).

³A Hilbert space is a regular real, or complex-valued, vector space with an inner product and a completeness property that assures converging limits will exist within the space itself.

146 **2.2. A change in choice perspective**

147 In quantum mechanics, two observables of a system are considered *incompatible* if a measurement
148 of one of them influences the outcome of the other. Conversely, two observables are compatible
149 if they do not influence each other.⁴ Thus in the context of our model, if two choices have no
150 relation to each other and their respective answers do not impact each other, they are compatible.
151 In such cases, the *same* belief state vector - albeit with *different* components dedicated to each of
152 the choice tasks - can invariably be used for the two tasks. However, if we had two tasks which
153 were related to each other by simple variation of some concrete attributes and hence require the
154 *same* components of the belief state vector - then the belief state needs to be updated as well.
155 For instance, in repeated choice tasks with only modified attributes of the alternatives, the belief
156 state of the decision-maker is updated in line with the cognitive process associated with each new
157 choice. Mathematically, the adaptation of the belief state to the different values of the attributes
158 is determined by immediate implementation⁵ in the vector components, Eq. 3, and effectively
159 corresponds to a rotation between the two state vectors (Hancock et al., 2020).

160 However, ‘incompatible’ choice tasks at a deeper level - when a pair of choices impact each
161 other on different components of the belief state - require different belief vectors for each of the
162 tasks. To give a more detailed example of such task ‘incompatibility’, consider a scenario where
163 the decision-maker has to choose their *favourite* and *least favourite* alternative from a set. The
164 sensitivities for what constitutes the best alternative may not be equivalent to what constitutes the
165 worst. This can be represented in quantum models through different vectors for an alternative being
166 the best compared to the same alternative being the worst. To capture the change of perspective
167 (considering the best, to considering the worst), a ‘quantum rotation’ is required, which maps
168 the belief state vector representing the choice of alternatives as being the best, to the belief state
169 vector representing the choice of alternatives as being the worst - and where the projection on
170 the respective axes remain with their interpretation of providing the amplitudes for the respective
171 alternatives. One can equivalently describe this rotation from a passive perspective in which the
172 belief state remains invariant but the basis is rotated in the opposite direction. Hancock et al. (2020)
173 have shown that such rotations (in Hilbert space) can capture the difference in the representation
174 (value) of an alternative when evaluated as best compared to when evaluated as worst. In this paper,
175 we use the same concept of a quantum rotation to capture changes of perspective in moral choice
176 scenarios. We also introduce a supplementary method based on inserting complex phases at the
177 level of attribute value functions in the belief state vectors to implement an alternative perspective
178 operation. We thus assume that choices under moral contexts involve more of a dilemma within
179 the deliberation process, with these model extensions capturing this additional process.

180 In a given choice context, we assume that an individual would evaluate the scenario differently
181 if they were first asked explicitly about the ‘ethical answerability’ of their choice. The presence
182 of a salient moral component may lead the decision-maker to a similar implicit intermediate
183 assessment and influence to consider their choice from a different perspective. In the event of
184 such an intermediate assessment of the moral attributes - from an effective change of perspective

⁴In case of incompatibility, a Heisenberg uncertainty relation can be derived which states that the product of the standard deviations of both observables should always be larger or equal to half the expectation value of their commutator. Compatible observables will hence be represented by commuting operators, see e.g. Griffiths (1994) section 3.4.

⁵Note that at this point, in stated preference settings, we make the assumption that previous choices do not impact the current choice.

185 on the choice - the choice proportions for the alternatives will have changed depending on the
 186 acceptance or dismissal of the moral components (see Figure 2).

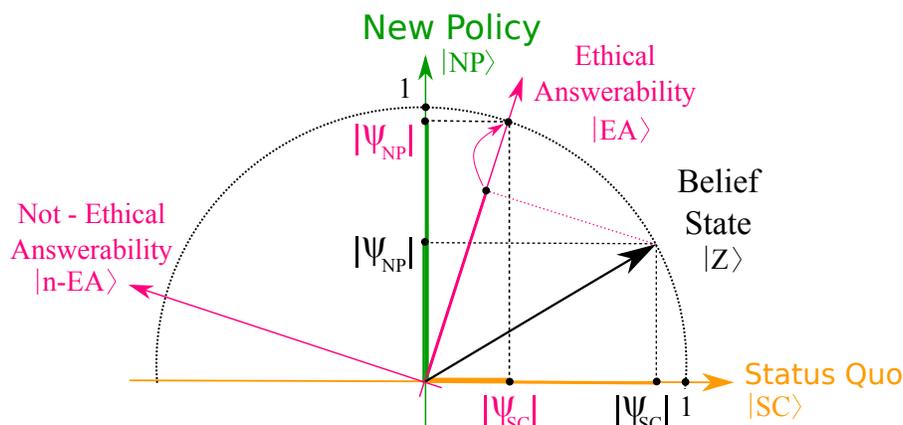


FIGURE 2 : Schematic representation of making implicit consecutive binary choices under quantum probability theory in the geometric quantum-like model; first ‘Ethical Answerability’ or ‘Not - Ethical Answerability’, followed by ‘New Policy’ or ‘Status Quo’. The striking ethical attribute(s) of the alternatives may induce an implicit recasting of the belief state on the basis $\{|EA\rangle, |n-EA\rangle\}$ and will, in this particular example, increase the belief support for the choice ‘New Policy’ on a *positive* outcome for ‘Ethical Answerability’ since the amplitude norm $|\psi_{NP}|$, in pink, is then larger than amplitude norm $|\psi_{NP}|$, in black, and the reverse is true for the ‘Status Quo’ scenario. Notice that while the initial belief state $|Z\rangle$ only had some latent tendency for responding ‘Ethical Answerability’, after the positive outcome, the updated belief state coincides with the ethical answerability belief state $|EA\rangle$ (pink arrow). Notice that the effect of the intermediate implicit measurement - with a given outcome - is equivalent to applying an active rotation to the belief state $|Z\rangle$ to either $|EA\rangle$ or $|n-EA\rangle$. The effective implemented rotation for the decision-maker’s implicit change of perspective encompasses both tendencies.

187 Hence in general, under a quantum model, when a decision-maker makes a choice - albeit
 188 implicit - this will update their belief state. If, for example, they decide that a particular alternative
 189 is ethically answerable, their state vector would then momentarily be equivalent to the ‘Ethically
 190 Answerable’ vector itself in the span of the two alternatives. This results in a change in the
 191 ‘lengths’ of projection onto the vectors representing the choice of the New Policy or the Status
 192 Quo alternative. We follow [Chorus et al. \(2018\)](#) by defining a new policy as involving a ‘*taboo*
 193 *trade-off*’ if a decision-maker could choose to decrease tax or travel time (a concrete attribute) at
 194 the cost of increasing the number of injuries or deaths (a moral attribute). Thus, in this example,
 195 under choice tasks that feature taboo trade-offs, the decision-maker is more likely to choose
 196 the new policy if they first decide that it is ethically answerable, and is less likely to choose it
 197 otherwise. Both tendencies are present in the decision-maker’s belief state, hence the implemented
 198 rotation for the decision-maker’s implicit change of perspective results effectively from a weighted
 199 combination of the two possible positions. The result of this is that quantum models can capture
 200 a change in perspective through a quantum rotation, which can be mathematically represented
 201 simply by estimating the impact a change of basis (passive) - or change of the belief state (active)
 202 - has on the ‘lengths’ of projections (Sections 3.1.3, 3.2.3). Besides implementing the change

203 of perspective through a quantum rotation of the belief state vector, we also implement such a
204 change of projection ‘lengths’ by the insertion of a complex phase on the attribute values in the
205 belief states, (Sections 3.1.4, 3.2.4). In the latter case, the change of projection ‘length’ results
206 from a constructive or destructive interference between the complex summands within each belief
207 state component itself. This complex phase method is similar to the more encompassing quantum
208 rotation method in its effect of summing complex components but differs in that this interference
209 occurs at the more basal level of each attribute itself. Since specific complex phasing can augment
210 the effect of moral attributes in the moral choice scenarios, this approach implements a perspective
211 operation by a more detailed process than the encompassing effect of a quantum rotation.

212 **2.3. Quantum theory and formal modelling of moral choices in psychology**

213 Whilst choice models with a quantum logic framework have not yet been tested on moral choice
214 data, there have been a number of applications of quantum logic to experiments for paradigms with
215 a moral component (where, for example, decision-makers may make choices that impact a number
216 of other individuals) in cognitive psychology. In particular, quantum probability theory has been
217 used to explain ‘interference’ effects where an additional decision task impacts the probability
218 of a subsequent decision for an action. For example, [Busemeyer et al. \(2009\)](#) tested the impact
219 of additionally asking decision-makers to categorise a digitally modified face - according to pre-
220 learned ad-hoc criteria - as ‘good’ or ‘bad’, before choosing how to respond by either a ‘withdraw’
221 or ‘attack’ action, and in which a bonus was provided for responding with the action ‘attack’ after
222 categorisation ‘bad’, or the action ‘withdraw’ after the category ‘good’, and a penalty otherwise.
223 Their study found that the quantum approach could be used to accurately capture the difference
224 in action responses with and without the categorisation task. Furthermore, in simulated jury
225 decision-making experiments, where participants read strong or weak defences and prosecutions,
226 quantum probability theory provided a better account of the ordering effects that were observed
227 compared to models based on classical probability ([Trueblood and Busemeyer, 2010](#)). Ordering
228 effects observed when participants state opinions about political figures can also be explained by
229 quantum cognition ([Pothos and Busemeyer, 2013](#)). In the context of a ‘taboo trade-off’, where
230 an individual can sacrifice ‘moral’ features in favour of ‘concrete’ features, a similar interference
231 may take place in that a decision-maker may not wish to appear ‘unethical’ or expose socially
232 undesirable choices. Similarly, an individual may consider their own welfare differently if they are
233 also required to consider the welfare of their partner.⁶ For this reason, we use quantum models to
234 test for interference effects in both of the choice datasets considered in this paper.

235 **2.4. Mathematical outline for basic quantum choice models**

236 Whilst the quantum approach provides a convenient structure for capturing phenomena in cognitive
237 psychology, its operationalisation into a choice model is less simple. The key component (as
238 discussed in detail by [Hancock et al. 2020](#)) is that a decision-maker has some ‘belief state’ $|Z\rangle$
239 regarding their preferences over alternatives presented in the experimental paradigm. When a
240 decision-maker makes a choice, their state goes from ‘indefinite’ to ‘definite’, by projecting their
241 belief state onto the vector representing the chosen alternative, where we further assume that the

⁶A recent theoretical model by [Yilmaz \(2019\)](#) proposes unitary transformations of the choice maker’s belief state based on first-person perspectives on imagined belief states of third-person agents to produce an effective ethical choice outcome. In contrast, our model implements the choice maker’s implicit intermediate belief state rotation to potentially consider their choice from their ethically concerned perspective, or not.

242 presented alternatives are mutually exclusive and exhaust all choice possibilities. This means that
 243 the choice probability, $Pr[Alt_j]$, for a specific alternative Alt_j , is given by the modulus square of
 244 the amplitude for that alternative appearing in the decision-maker's belief state

$$Pr[Alt_j] = |\psi_j|^2, \quad (1)$$

245 where $|Z\rangle$ is a column vector, with $|Z\rangle = (\psi_1 \dots \psi_j \dots \psi_J)^\tau$. Since the belief state vector is
 246 normalised, the probabilities for the alternatives add up to 1:

$$\sum_{j=1}^J |\psi_j|^2 = 1, \quad (2)$$

247 Consequently, we must build quantum choice models by developing methods for defining a belief
 248 state vector based on functions of the attributes of the alternatives. For the applications in this
 249 paper, we consider an approach based on the 'quantum amplitude model', as developed in [Hancock
 250 et al. \(2020\)](#). The key feature of the quantum amplitude model (QA) is that the amplitudes of
 251 each alternative are explicitly implemented with the use of some value function. This allows us
 252 to directly estimate the probabilities with which each alternative is chosen. Whilst a number of
 253 different value functions can be used, we focus on the use of regret-like functions ([Chorus, 2010](#))
 254 for the applications in this paper. The amplitude for an alternative i for individual n in choice task
 255 t is thus defined as:

$$\psi_{nti} = \left(\delta_{QA,i} + \sum_{j \neq i}^J \sum_{k=1}^K \ln(1 + e^{\beta_k(x_{ntik} - x_{ntjk})}) \right) / \sqrt{\mathcal{N}_{nt}}, \quad (3)$$

256 where $j = 1, \dots, J$ is an index across alternatives, $k = 1, \dots, K$ is an index across attributes, $\delta_{QA,i}$ is
 257 an alternative specific constant, β_k are attribute-specific weights and \mathcal{N} is a normalisation factor.
 258 This factor, which ensures that the probabilities with which each alternative is chosen sum to one,
 259 is obtained from the sum of the squared moduli numerators:

$$\mathcal{N}_{nt} = \sum_i^J \left| \left(\delta_{QA,i} + \sum_{j \neq i}^J \sum_{k=1}^K \ln(1 + e^{\beta_k(x_{ntik} - x_{ntjk})}) \right) \right|^2. \quad (4)$$

260 Note that given the probabilities with which the different alternatives are chosen are based on
 261 squaring these amplitudes, the same probabilities will be generated if all amplitudes are multiplied
 262 by the same factor - as opposed to the *addition* of the same term. Thus the number of additive
 263 constants that are identifiable is equal to the number of alternatives. Additionally, the equations
 264 as presented here imply that the amplitudes are in real-valued space, with operations moving the
 265 amplitudes into complex space introduced in the following section. Our approach thus makes
 266 explicit use of complex-valued operations and hence enacts interference effects which cannot be
 267 obtained in the real-valued trigonometric approach of [Lipovetsky \(2018\)](#). Alternative methods for
 268 capturing moral features can still use the above implementations, with for example, the use of
 269 additional constants or separate β -coefficients depending on the choice context.

270 **2.5. Quantum model perspective operations for a change in choice context**

271 We consider two possible extensions (which we label ‘perspective operations’) to the basic quantum
 272 choice models described above, with each extension attempting to capture a ‘change of perspective’
 273 for the taboo or moral trade-off in a different way.

274 1. A ‘**quantum rotation**’ (models QAR-1 and QAR-2). We follow [Hancock et al. \(2020\)](#) in
 275 using Pauli matrices to implement a rotation operation on the belief state itself. For scenarios
 276 involving two alternatives, this rotation occurs in a 2-dimensional Hilbert space, with the
 277 rotation matrix generated by Pauli matrices;

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (5)$$

278 The rotation operator, R , itself - about axis $\mathbf{n} = (n_x, n_y, n_z)$ and over angle ϑ - is then given
 279 by;

$$R = e^{-i\vartheta \mathbf{n} \cdot \boldsymbol{\sigma}}, \quad (6)$$

280 where $\mathbf{n} \cdot \boldsymbol{\sigma}$ gives some combination of the Pauli factors, with the restriction that $|\mathbf{n}| = 1$.

281 For choice scenarios involving three alternatives, as in the second dataset, we apply two
 282 consecutive quantum rotations on different pairs of alternatives. Given the importance of
 283 ordering within quantum models, the choice of pairs and order in which the two rotations
 284 are made will impact the outcome.

285 To apply the rotation, we use the initial belief state, Ψ_0 , which is simply the vector with
 286 amplitudes for each alternative using Eq. (3) - i.e. model QA without Taboo trade-off
 287 parameters. We then obtain the belief state for the changed perspective, Ψ_f , by applying
 288 the rotation matrix:

$$\Psi_f = R\Psi_0. \quad (7)$$

289 The rotation thus appropriately adjusts the amplitudes for the different alternatives depending
 290 on the impact that the change of perspective has on the choice being made. A matrix R with
 291 zero off-diagonal elements (i.e. if we have $\mathbf{n} \cdot \boldsymbol{\sigma} = \sigma_z$) would thus result in no change in the
 292 probabilities with which each alternative is chosen. As a contrast, $\vartheta = \pi/2$ and $\mathbf{n} \cdot \boldsymbol{\sigma} = \sigma_y$
 293 results in the probabilities for a pair of alternatives perfectly swapping.

294 We consider two different options for constructing R :

295 (a) A rotation, R_1 , that uses a single estimated parameter. It is based on previous work
 296 where we used a Hamiltonian approach to quantum modelling (see [Hancock et al.](#)
 297 [2020](#)). We implement the rotation with a fixed constant ($\vartheta = \pi/2$) and modulate it
 298 with a single parameter (h) that also weights the Pauli matrices:

$$R_1 = e^{-i\frac{\pi}{2}\sqrt{1+h^2}\mathbf{n} \cdot \boldsymbol{\sigma}}, \quad (8)$$

299 with $\mathbf{n} = \left(0, \frac{h}{\sqrt{1+h^2}}, \frac{1}{\sqrt{1+h^2}}\right)$.

300 (b) A rotation, R_2 , that uses up to three estimated parameters. The angle ϑ is estimated
 301 directly and ω_1 and ω_2 are axis parameters used to weight the Pauli matrices, with
 302 $\mathbf{n} = (\sin(\omega_1), \cos(\omega_1) \cdot \cos(\omega_2), \cos(\omega_1) \cdot \sin(\omega_2))$.

303 2. The introduction of ‘**complex phases**’ (model QAP), such that the amplitudes for the choice
 304 alternatives contain real and imaginary parts. We implement these complex phases in the QA
 305 model by multiplying $\ln(1 + e^{\beta_k(x_{ntik} - x_{mjk})})$ in Eq. (3) with $e^{i\varphi_k}$. Note that we could estimate
 306 a different φ_k for each attribute k , or alternatively have a simpler structure such that a single
 307 additional parameter is estimated ($\varphi_k = \varphi, \forall k$).

308 To apply a model with a rotation, we first estimate amplitudes for each alternative based on the
 309 basic model QA. Then, under choice scenarios in which there is a ‘change of perspective’, we apply
 310 either of two implementations of the quantum rotation (QAR-1 ad QAR-2). The second feature of
 311 the complex phases is instead implemented directly into the basic model QA. It thus assumes that
 312 moral attributes are ‘treated differently’ to others. If these attributes are very different, then the
 313 estimates for their respective phases, φ_k , will be different, allowing interference interactions.

314 3. EMPIRICAL APPLICATION

315 In this section, we present the results of two case studies. In each case, we first detail the dataset
 316 that is used for testing our quantum choice models. We then apply our quantum model under
 317 basic settings before introducing quantum rotations for specific choice contexts or alternatively
 318 adding complex phases in the specification. We conclude by providing combined models with
 319 both rotations and complex phases.

320 3.1. Quantum modelling for taboo trade-offs

321 3.1.1. Description of data

322 The first dataset we use involves ‘taboo trade-offs’ and comes from [Chorus et al. \(2018\)](#) (and
 323 is thus henceforth labelled the ‘taboo trade-off dataset’). Decision-makers choose between the
 324 introduction of a new transport policy or keeping the status quo. To simplify the choice scenarios,
 325 each new policy simply offered an increase or decrease compared to the status quo for four
 326 attributes, with shifts by ± 300 EUR vehicle ownership tax, ± 20 minutes travel time for each
 327 car commuter per day, ± 100 serious injuries in traffic accidents and ± 5 deaths in traffic accidents.
 328 This results in a total of 16 possible new policies, which are offered in turn to each of 99 decision-
 329 makers, resulting in a dataset with a total of 1,584 choices. For consistency, we follow [Chorus](#)
 330 [et al. \(2018\)](#) by defining a choice as involving a ‘taboo trade-off’ if a decision-maker could choose
 331 a policy that involves decreasing tax or travel time (a concrete attribute) at the cost of increasing
 332 the number of injuries or deaths (a moral attribute). One could of course argue that a scenario
 333 that increases injuries and reduces time or cost is not a taboo trade-off if deaths are also reduced
 334 at the same time. We also follow [Chorus et al. \(2018\)](#) in including all 16 choice scenarios in our
 335 dataset to aid a direct comparison with their ‘Taboo Trade-off Aversion’ model (TTOA). Two of
 336 these scenarios include dominated alternatives (Scenarios 1 and 5 in Table 3). A summary of the
 337 observed share of choices under the different scenarios is given in Table 1.

338 For all attributes, we observe that the new policy is more likely to be chosen if there is a
 339 decrease in the attribute, as expected. Additionally, we observe that individuals are less likely to
 340 pick the new policy if it falls into the category of a taboo trade-off. The observed shares for each

TABLE 1 : Observed shares for choosing the new policy or the status quo depending on the attribute change

| | | Chosen alternative | |
|-----------|----------|--------------------|------------|
| | | New Policy | Status Quo |
| Tax | Decrease | 50.88% | 49.12% |
| | Increase | 20.32% | 79.68% |
| Time | Decrease | 43.44% | 56.56% |
| | Increase | 27.78% | 72.22% |
| Injuries | Decrease | 53.28% | 46.72% |
| | Increase | 17.92% | 82.08% |
| Deaths | Decrease | 47.72% | 52.28% |
| | Increase | 23.48% | 76.52% |
| Taboo | Yes | 30.08% | 69.92% |
| Trade-Off | No | 42.72% | 57.28% |

341 specific choice scenario are given together with model results in Table 3. This dataset is suitable
 342 for quantum choice modelling as decision-makers may not process the different attributes or the
 343 different choice tasks in the same way. Thus, quantum rotations and complex phases may both
 344 provide a method for capturing these differences.

345 3.1.2. Basic models for the taboo trade-off dataset

346 For the first set of models tested, we do not include either quantum rotations or complex phases in
 347 the specifications, so as to test the basic structure of the quantum models.

348 We test models without any parameters to control for the presence of a taboo trade-off, as well
 349 as models with an additional constant added to represent the presence of a taboo-trade off. We
 350 have a parameter to capture the relative importance of each attributes, and test the quantum model
 351 as specified by Eq. (3). We now look in turn at the amplitudes for the status quo (SQ) and new
 352 policy (NP) options, where we do not show an index for individuals, n , as all participants complete
 353 all 16 choice tasks and there is no variation in the attributes at the individual level:

$$\begin{aligned} \psi_{t,SQ} = & \left(\delta_{SQ} + \delta_{base} + \ln(1 + e^{-\beta_{TT} \cdot \Delta_{t,TT}}) + \ln(1 + e^{-\beta_{Tax} \cdot \Delta_{t,Tax}}) \right. \\ & \left. + \ln(1 + e^{-\beta_{DE} \cdot \Delta_{t,DE}}) + \ln(1 + e^{-\beta_{IN} \cdot \Delta_{t,IN}}) \right) / \mathcal{N}_t, \end{aligned} \quad (9)$$

354 and for the new policy:

$$\begin{aligned} \psi_{t,NP} = & \left(\delta_{Taboo} \cdot z_{t,taboo} + \delta_{base} + \ln(1 + e^{\beta_{TT} \cdot \Delta_{t,TT}}) + \ln(1 + e^{\beta_{Tax} \cdot \Delta_{t,Tax}}) \right. \\ & \left. + \ln(1 + e^{\beta_{DE} \cdot \Delta_{t,DE}}) + \ln(1 + e^{\beta_{IN} \cdot \Delta_{t,IN}}) \right) / \mathcal{N}_t, \end{aligned} \quad (10)$$

355 where t is an index across choice tasks, $t = 1..16$ and, $\Delta_{t,x} = 1$ if attribute x increases under the new
 356 policy and $\Delta_{t,x} = -1$ if the attribute decreases under the new policy, and where the normalisation

357 factor \mathcal{N}_i satisfies Eq. (4). We include relative importance parameters for the four different
 358 attributes, β_{TT} for travel time, β_{Tax} for travel tax, β_{DE} for number of deaths and β_{IN} for number of
 359 injuries. As all of these attributes are unfavourable - less is better - we expect negative estimates for
 360 these coefficients. This leads to a decrease in the amplitude of the new policy if $\Delta_{t,x} = 1$ (i.e. there
 361 is an increase in the attribute), resulting in a smaller probability. We add a constant, δ_{base} , to both
 362 numerators and a constant, δ_{SQ} , that allows us to statistically test the underlying bias towards the
 363 status quo. As a contrast to random utility models, the additional constant here does not result in
 364 an overspecification, with an increased value for δ_{base} corresponding to less deterministic choices.
 365 Under the basic model that accounts for the presence of a taboo trade off, we additionally estimate
 366 a taboo trade-off constant where appropriate, δ_{Taboo} , which is multiplied by $z_{i,taboo}$, an indicator
 367 that takes a value of one for choice tasks where there is the presence of a taboo trade-off, and a
 368 value of zero otherwise. In our model that does not account for taboo trade-offs, we fix δ_{Taboo}
 369 to a value of zero. Additionally, as there are no attribute levels in this dataset, multiplying all
 370 parameters by the same constant results in the same likelihood for the quantum amplitude model.
 371 We consequently fix the first β -coefficient to a value of -1 to avoid an overspecification. This will
 372 result in the QA model having the same number of free parameters as the logit model.

373 We compare our quantum models to logit models that are equivalent to those specified by
 374 [Chorus et al. \(2018\)](#). The utility for the two alternatives is defined as:

$$U_{t,SQ} = (\delta_{SQ} - \beta_{TT} \cdot \Delta_{t,TT} - \beta_{Tax} \cdot \Delta_{t,Tax} - \beta_{DE} \cdot \Delta_{t,DE} - \beta_{IN} \cdot \Delta_{t,IN}) + \varepsilon_{t,SQ}, \quad (11)$$

375 and:

$$U_{t,NP} = (\delta_{taboo} \cdot z_{i,taboo} + \beta_{TT} \cdot \Delta_{t,TT} + \beta_{Tax} \cdot \Delta_{t,Tax} + \beta_{DE} \cdot \Delta_{t,DE} + \beta_{IN} \cdot \Delta_{t,IN}) + \varepsilon_{t,NP}, \quad (12)$$

376 where ε is a type I extreme value error. The addition of δ_{taboo} to the utility for the new policy in
 377 the presence of a taboo trade-off, then gives us the ‘Taboo Trade-off Aversion’ model (TTOA) as
 378 specified by [Chorus et al. \(2018\)](#).

379 The results of our quantum and logit models are given in Table 2, where we first report basic
 380 logit and basic quantum models, before reporting models that include a special treatment for the
 381 taboo trade-offs (Logit-t and QA-t, respectively). For all of the models in this paper, we use R
 382 packages maxLik ([Henningsen and Toomet, 2011](#)) and Apollo ([Hess and Palma, 2019](#)).

383 Without any parameter for a taboo trade-off, the quantum amplitude (QA) model is outperformed
 384 by the logit model. Notably, the model appears to find very similar relative ratios for the different
 385 β -attribute coefficients as logit. The addition of a taboo parameter (which is significant in each
 386 model) results in a reduction in the estimates for injuries and deaths for both models. It improves
 387 the fit of the QA model slightly more than the logit model, but the logit model still has the best
 388 log-likelihood and adjusted ρ^2 value at this point.⁷ For the basic models, the best overall BIC value
 389 is obtained by a logit model without a taboo parameter.

390 3.1.3. Models with quantum rotations for the taboo trade-off dataset

391 We next turn to models with additional rotations implemented in the presence of a taboo trade-off,
 392 which attempt to capture the ‘change of perspective’, as described in Section 2.5. Thus, if the
 393 decision-maker can decrease travel time or tax at the cost of increasing the number of fatalities or
 394 serious injuries, a rotation is applied.

⁷Note that ‘Logit-t’ is identical to the ‘Generic Taboo Trade-Off Aversion’ (TTOA) model as described by [Chorus et al. \(2018\)](#).

TABLE 2 : Results of all models applied to the taboo trade-off dataset, together with all parameter estimates, where \circ and \star indicate attribute pairs which have the same phase.

| Type | | Basic models | | | | Quantum rotations | | Models with complex phases | | | | | Combined |
|------------------------------------|----------------------------|--------------|--------------|---------|--------------|-------------------|--------------|----------------------------|------------------|------------------|------------------|--------------|------------------|
| Specification | | Logit | QA | Logit-t | QA-t | QAR-1 | QAR-2 | QAPh-1 | QAPh-2a | QAPh-2b | QAPh-2c | QAPh-3 | QAC |
| Free parameters | | 5 | 5 | 6 | 6 | 6 | 7 | 6 | 7 | 7 | 7 | 9 | 9 |
| Log-likelihood | | -721.23 | -725.40 | -719.47 | -722.61 | -717.94 | -717.77 | -719.17 | -712.94 | -719.16 | -718.83 | -712.79 | -712.35 |
| BIC | | 1479.29 | 1487.63 | 1483.15 | 1489.43 | 1480.09 | 1487.12 | 1482.54 | 1477.45 | 1489.90 | 1489.24 | 1491.89 | 1491.02 |
| B-S test p-value (vs. RRM-t) | | | | | | 0.0402 | 0.2655 | 0.2181 | 0.0008 | | | 0.0184 | 0.0111 |
| Adj. ρ^2 | | 0.3386 | 0.3348 | 0.3392 | 0.3364 | 0.3406 | 0.3399 | 0.3395 | 0.3443 | 0.3386 | 0.3389 | 0.3426 | 0.3430 |
| Average probability of choosing NP | No taboo (before rotation) | 41.57% | 41.22% | 42.71% | 42.12% | 41.86% | 42.01% | 42.06% | 43.07% | 42.08% | 42.23% | 43.04% | 42.87% |
| | Taboo (after rotation) | - | - | - | - | 30.69% | 30.36% | - | - | - | - | - | 30.16% |
| β_{Tax} | est. | -0.4888 | -1.0000 | -0.5232 | -1.0000 | -1.0000 | -1.0000 | -1.3989 | -1.4536 | -1.3963 | -1.3679 | -1.4293 | -1.6455 |
| | rob.t-rat. | -10.31 | fixed | -10.05 | fixed | fixed | fixed | -9.05 | -6.88 | -9.31 | -9.45 | -5.22 | -5.70 |
| β_{TT} | est. | -0.2598 | -0.5271 | -0.2834 | -0.5675 | -0.5225 | -0.5304 | -0.7442 | -0.8368 | -0.7476 | -0.7792 | -0.8517 | -0.9638 |
| | rob.t-rat. | -6.54 | -5.08 | -7.01 | -5.83 | -5.38 | -5.40 | -6.56 | -5.23 | -6.79 | -6.59 | -5.12 | -4.53 |
| β_{IN} | est. | -0.5548 | -1.1239 | -0.5052 | -0.9660 | -1.1731 | -1.1201 | -1.5786 | -1.8668 | -1.5764 | -1.6693 | -1.7748 | -1.9672 |
| | rob.t-rat. | -10.31 | -7.26 | -8.99 | -6.75 | -7.49 | -6.84 | -8.84 | -9.21 | -8.90 | -7.05 | -8.11 | -7.74 |
| β_{DE} | est. | -0.3957 | -0.7870 | -0.3444 | -0.6627 | -0.8458 | -0.7988 | -1.1301 | -1.4356 | -1.1364 | -1.1128 | -1.5081 | -1.5517 |
| | rob.t-rat. | -9.43 | -6.95 | -7.80 | -6.32 | -7.15 | -6.15 | -8.22 | -7.93 | -7.13 | -8.24 | -5.22 | -6.61 |
| δ_{SQ} | est. | -0.9269 | -0.9208 | -0.6293 | -0.6244 | -0.9704 | -0.8747 | -1.7840 | -1.2720 | -1.7945 | -1.8456 | -1.2543 | -1.2672 |
| | rob.t-rat. | -8.17 | -6.95 | -4.12 | -4.35 | -7.02 | -5.10 | -6.80 | -9.52 | -6.28 | -6.53 | -8.35 | -7.90 |
| δ_{base} | est. | | -0.2995 | | -0.5226 | -0.7632 | -0.8383 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| | rob.t-rat. | | -1.37 | | -2.65 | -4.14 | -4.38 | fixed | fixed | fixed | fixed | fixed | fixed |
| δ_{taboo} | est. | | | -0.4409 | -0.3506 | | | | | | | | |
| | rob.t-rat. | | | -2.30 | -2.75 | | | | | | | | |
| h | est. | | | | | -0.2779 | | | | | | | |
| | rob.t-rat. | | | | | -6.07 | | | | | | | |
| ω | est. | | | | | | -1.85 | | | | | | 3.0729 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | -94.29 | | | | | | 28.79 |
| ϑ | est. | | | | | 1.5708 | 1.7257 | | | | | | 2.0577 |
| | rob.t-rat. (vs $\pi/2$) | | | | | fixed | 0.91 | | | | | | 0.43 |
| φ_{Tax} | est. | | | | | | | -0.5644 $^\circ$ | -0.9913 $^\circ$ | -0.5797 $^\circ$ | -0.7790 $^\circ$ | -0.9584 | -1.1296 $^\circ$ |
| | rob.t-rat. | | | | | | | -6.23 | -6.27 | -3.23 | -4.25 | -4.77 | -7.56 |
| φ_{TT} | est. | | | | | | | -0.5644 $^\circ$ | -0.9913 $^\circ$ | -0.5540 \star | -0.4428 \star | -1.0188 | -1.1296 $^\circ$ |
| | rob.t-rat. | | | | | | | -6.23 | -6.27 | -3.60 | -3.40 | -4.21 | -7.56 |
| φ_{IN} | est. | | | | | | | -0.5644 $^\circ$ | 0.3904 \star | -0.5797 $^\circ$ | -0.4428 \star | 0.3367 | 0.4453 \star |
| | rob.t-rat. | | | | | | | -6.23 | 2.03 | -3.23 | -3.40 | 1.77 | 2.56 |
| φ_{DE} | est. | | | | | | | -0.5644 $^\circ$ | 0.3904 \star | -0.5540 \star | -0.7790 $^\circ$ | 0.4794 | 0.4453 \star |
| | rob.t-rat. | | | | | | | -6.23 | 2.03 | -3.60 | -4.25 | 2.23 | 2.56 |
| Rotation matrix | R[1,1] | | | | | -0.15-0.95i | -0.15+0.95i | | | | | | -0.47-0.88i |
| | R[1,2] | | | | | 0.27+0.00i | 0.27+0.00i | | | | | | -0.06+0.00i |
| | R[2,1] | | | | | -0.27+0.00i | -0.27+0.00i | | | | | | 0.06+0.00i |
| | R[2,2] | | | | | -0.15+0.95i | -0.15-0.95i | | | | | | -0.47+0.88i |

395 The models in this section are based on those in Section 3.1.2, with the amplitudes being
 396 estimated equivalently using Eqs. (9) and (10). However, instead of adding a constant to capture
 397 the presence of a taboo trade-off, an additional rotation is applied to the estimated amplitudes
 398 using Eq. (7). We test two different rotations, with each based on the Pauli matrices, as described
 399 in Section 2.5.

400 1. We first use a rotation matrix, R_1 , with one free parameter, h , for weighting the Pauli matrices
 401 $n_y = \frac{h}{\sqrt{1+h^2}}$, $n_z = \frac{1}{\sqrt{1+h^2}}$ and set the rotation angle $\vartheta = \frac{\pi}{2} \cdot \sqrt{1+h^2}$. Notice that an estimate
 402 of $h = 0$ would indicate no change in probability. Positive estimates indicate a shift towards
 403 alternative 1, whereas negative estimates indicate a shift towards alternative 2.

404 2. We next use a rotation matrix, R_2 , based on our second method using trigonometric functions
 405 to define the weights for $|\mathbf{n}|$. We find that fixing $n_x = 0$ results in no loss of model fit, leaving
 406 us with two free rotation parameters: one for the angle, ϑ , and another ω , where we set
 407 $n_y = \cos(\omega)$ and $n_z = \sin(\omega)$ (which guarantees $|\mathbf{n}| = 1$).

408 The results of models with quantum rotations are again given in Table 2. This table also reports
 409 p-values from Ben-Akiva and Swait tests (Ben-Akiva and Swait, 1986) for non-nested models,
 410 assessing whether the quantum models have a statistically better fit than the TTOA (Logit-t) model.
 411 This table further reports the average probability of choosing the new policy (NP) before and after
 412 the quantum rotation is applied to a choice scenario which contains a taboo trade-off (the observed
 413 choice proportions appear in Table 1).

414 For model QAR-1, which has the quantum rotation implemented, we see a significant improvement
 415 in log-likelihood from the addition of 1 parameter. This quantum model now has a better BIC than
 416 the TTOA model (1,483.15) and is statistically better at the 5% level, with a p-value of 0.040 from
 417 the Ben-Akiva and Swait test. The addition of a second free parameter in the model (QAR-2) does
 418 not result in a significant improvement in the log-likelihood compared to the QAR-1 model.

419 In line with the results of Chorus et al. (2018) and Table 1, we observe that across all models,
 420 the presence of a taboo trade-off results in the decision-maker being less likely to choose the
 421 New Policy alternative. As the number of model parameters increases, the average probabilities
 422 under the model become increasingly closer to matching the observed share of new policy choices
 423 (30.08% when there is a taboo trade-off, 42.72% when there is not, Table 1). For QAR-2, we
 424 observe that the rotation, on average, reduces the probability of choosing the new policy. Under
 425 QAR-1, the opposite is true. Whilst this result may appear counterintuitive, we observe a greater
 426 estimate for β_{DE} (see Table 2) in QAR-1 in comparison to QA, demonstrating that the additional
 427 flexibility of including a rotation allows for more extreme estimates to help capture choices in
 428 general. We will return to the impact of quantum rotations on the probabilities of choosing the
 429 alternatives in more detail later (see Section 3.1.5).

430 3.1.4. Models with complex phases for the taboo trade-off dataset

431 An alternative mechanism for capturing different ‘processes’ with a quantum choice model is the
 432 implementation of complex phases, as described in Section 2.5. As with models with quantum
 433 rotations, we have a number of options for how many free parameters to use in the specifications
 434 for the quantum choice models. We consider the following three possibilities:

- 435 1. A single complex phase, φ , for all of the attributes, such that all $\ln(1 + e^{\beta_x \Delta_x})$ are replaced
 436 with $e^{-i\varphi} \cdot \ln(1 + e^{\beta_x \Delta_x})$ in Eqs. (9) and (10). This implementation of phases tests whether
 437 the introduction of complex phases improves the model performance in general.
- 438 2. Two complex phases, φ_1 and φ_2 , each respectively applied to two attributes. This gives us
 439 three distinct configurations. Our focus of interest is on the configuration with one phase
 440 applied to the two moral attributes and the other phase applied to the two concrete attributes.
 441 If this model is significantly better than the other configurations, it would suggest that the
 442 moral and concrete attributes are indeed ‘different’ and can be categorised as such.
- 443 3. Four complex phases with four free parameters, $\{\varphi_1, \varphi_2, \varphi_3, \varphi_4\}$, with a different phase for
 444 each attribute. This configuration allows us to test the performance of the introduction of
 445 relative complex phases overall.

446 The results of models with complex phases are given in Table 2. As with quantum rotations, we
 447 again observe that there is a significant improvement obtained by including complex phases. The
 448 first model offers a good improvement over the base QA model, but is not statistically better than
 449 the TTOA model. Further additional free parameters result in improvements in model fit. As these
 450 parameters are significantly different from zero (if $\varphi = 0$, then we have $e^{i0} = 1$, which corresponds
 451 to real-only amplitudes), we have evidence to reject models without complex phases in favour of
 452 models with complex phases. Note that the introduction of complex phases into the specification
 453 of the amplitudes (Eq. 3) means that we no longer have an overspecification by not fixing one
 454 of the β -coefficients. This is a direct result of having real-valued constants in the amplitudes.
 455 However, we still have five base parameters as the estimate for δ_{base} becomes insignificant, and is
 456 thus fixed to a value of zero. Crucially, the model results suggest that concrete and moral attributes
 457 are treated ‘differently’ in the cognitive choice process, as a substantial gain is found through the
 458 use of separate phases for the concrete and moral attributes, but not for other combinations of uses
 459 of two complex phases. Furthermore, we obtain insignificantly different estimates for the tax and
 460 time phases and the deaths and injuries phases when each parameter has a separate phase (model
 461 QAPh-3). This suggests that the concrete attributes are treated ‘equivalently’ in the cognitive
 462 choice process and similarly so for the moral attributes. In comparison to models with a quantum
 463 rotation, the models with complex phases record better BIC values, with the best adjusted ρ^2 value
 464 of 0.3443 for a model with complex phases compared to 0.3406 for a model with a rotation. This
 465 implies that the moral aspect in the choice tasks is better captured by a perspective operation that
 466 implements separate complex phases for moral and concrete attributes, as opposed to the inclusion
 467 of a rotation for particular choice tasks.

468 3.1.5. Combined model for the taboo trade-off dataset

469 For our final model, we test the use of a model that incorporates both a quantum rotation and
 470 complex phases simultaneously. Our final model for the taboo trade-off dataset is based on the
 471 best performing model thus far (QAPh-2a) combined with the use of a rotation based on Pauli
 472 matrices. It thus has two complex phase parameters (one for concrete attributes, and one for moral
 473 attributes), as well as two rotation parameters. This results in the model having an additional four
 474 parameters to capture the moral components in the choice tasks, on top of the five base parameters
 475 of the basic QA model.

476 The results of the combined model (QAC) are shown in Table 2. For this model, we observe
477 significant estimates for the parameters for the complex phases, where these are not significantly
478 different from the estimates for these parameters under a model without additional rotation parameters
479 (QAPh-2a). The combined model does not offer a significant improvement over the version with
480 complex phases, with the estimates for the rotation parameter ϑ not being significantly different
481 from $\pi/2$, indicating that the rotation has minimal impact. This implies that for this dataset,
482 complex phases and additional rotations are approximately equivalent.

483 However, there is evidence that there is still an effect by including the rotation, through consideration
484 of the results in Table 3. This table gives the probability of supporting the new policy under each of
485 the different choice scenarios before and after the quantum rotation is applied. Crucially, our final
486 model has smaller mean absolute deviations from the true share of support than the TTOA model
487 (which is unsurprising given that this model has more free parameters and records a statistically
488 significant improvement in the model fit). This is only the case for the ‘taboo tasks’ after the
489 implementation of the rotation, suggesting that the combined model still benefits from the inclusion
490 of the rotations. Note that a rotation is not like an additive constant, which would always result
491 in a bias towards one alternative. Instead, the combination of real and imaginary numbers (the
492 interference effect) results in a shift that may swing the probabilities in either direction, which
493 is hence unlikely to result in a direct bias towards one alternative. In this case, the rotation
494 almost always reduces the probability of choosing the new alternative. This is in line with our
495 expectations: the presence of a taboo trade-off reduces the likelihood of choosing the new policy.

496 **3.2. Quantum modelling for moral trade-offs involving a couple’s respective commutes**

497 *3.2.1. Description of data*

498 The second dataset we test involves decision-makers completing two distinct sets of choice tasks
499 based on an individual’s willingness to accept longer commutes for better salaries (see Beck and
500 Hess, 2016, for a detailed description of the survey). The first set of tasks involved trade-offs
501 between the individual’s current travel time and salary or an increased salary (of 500 or 1000 SEK
502 in net wage per month) at a cost of an increase in one-way travel time (of either 10 or 25 minutes).
503 The second set additionally included attributes for increased travel time and salaries for the partner
504 of the decision-maker (under the assumption that both the decision-maker and their partner both
505 commute to work), meaning that the decision-maker has to make choices about who to prioritise
506 (the dataset is thus henceforth referred to as the ‘couple commuter dataset’). All choice tasks
507 included a status quo alternative, a new alternative and an ‘I am indifferent’ option. A sample of
508 1,179 households (with both partners in each household, resulting in 2,358 individuals) completed
509 4 tasks for the first set involving only attributes affecting themselves, and 4 or 5 tasks for the
510 second set with attributes impacting both members of the household. This resulted in a total of
511 20,041 choice observations.

512 While the first set of choice tasks involves typical time-cost trade-offs that can potentially be
513 captured well with traditional choice models, the latter involves a more complex decision context
514 without any ‘crisp’ trade-off element in that there may not be a clear ethical protocol for how to
515 make the decision. This dataset thus provides another test for our quantum model features that
516 capture changes in choice context. The observed choice shares for the alternatives are given in
517 Table 4, where we see that a decision-maker is more likely to pick the status quo over the new
518 alternative if the choice task also includes attributes concerning their partner.

519 At the outset, it should already be noted that the presence of an ‘indifference’ option in a

TABLE 3 : Observed and theoretical choice probabilities in the taboo trade-off dataset. The ‘taboo trade-off’ occurs if a decision-maker chooses to decrease tax or travel time at the cost of increasing the number of injuries or deaths. The impact of the quantum rotations is rendered explicit; ‘Before’ is the probability of choosing the new policy without applying quantum rotation, ‘After’ is the probability with application of the quantum rotation. TTOA gives theoretical probabilities from the ‘Generic Taboo Trade-Off Aversion’ model (Chorus et al., 2018).

| Scenario | Attributes | | | | Taboo Trade-Off? | Share of support for New Policy | | | |
|--|------------|------|----------|--------|------------------|---------------------------------|----------------|-------------|-------|
| | Tax | Time | Injuries | Deaths | | Observed | TTOA (Logit-t) | QAC | |
| | | | | | | | before | after | |
| 1 | - | - | - | - | No | 98.0% | 93.6% | 97.5% | |
| 2 | - | - | - | + | Yes | 68.7% | 70.4% | 67.6% | 65.3% |
| 3 | - | - | + | + | Yes | 29.3% | 23.9% | 32.6% | 27.3% |
| 4 | - | + | + | + | Yes | 11.1% | 9.2% | 16.1% | 12.2% |
| 5 | + | + | + | + | No | 2.0% | 1.9% | 2.7% | |
| 6 | + | - | - | - | No | 62.6% | 64.3% | 63.3% | |
| 7 | + | + | - | - | No | 44.4% | 36.7% | 42.7% | |
| 8 | + | + | + | - | No | 4.0% | 7.1% | 3.5% | |
| 9 | - | + | - | + | Yes | 42.4% | 43.3% | 40.6% | 41.9% |
| 10 | + | - | + | - | Yes | 15.2% | 13.3% | 12.2% | 13.8% |
| 11 | - | - | + | - | Yes | 46.5% | 55.5% | 56.4% | 53.0% |
| 12 | - | + | - | - | No | 80.8% | 82.5% | 81.4% | |
| 13 | - | + | + | - | Yes | 30.3% | 28.7% | 29.5% | 29.2% |
| 14 | + | - | - | + | Yes | 22.2% | 22.6% | 21.0% | 24.2% |
| 15 | + | - | + | + | Yes | 5.1% | 3.7% | 7.3% | 4.6% |
| 16 | + | + | - | + | No | 7.1% | 12.8% | 9.1% | |
| Mean absolute deviation from true share of support (%; all choice tasks) | | | | | | 3.03 | 2.19 | 1.57 | |
| Mean absolute deviation from true share of support (%; taboo tasks only) | | | | | | 2.68 | 3.15 | 2.05 | |

520 SC survey calls for special attention in model specification. Indeed, as discussed by Hess et al.
521 (2014), the inclusion of an ‘indifference’ option means that non context-dependent models are
522 likely not suitable. To understand this point, note that making both the status quo and the alternative
523 option worse or better by the same amount, be this through changes in time, salary, or both,
524 should not affect the degree to which a decision-maker is indifferent between them. However,
525 in structures based on random utility maximisation (RUM), changes to time or salary for the
526 non-indifference options would change their utilities and hence their probabilities relative to the
527 indifference option, whose utility is unchanged. Hess et al. (2014) shows that on the contrary, as a
528 result of regret models using a value function that is reliant on pairwise comparisons of alternatives,
529 the same change in all non-indifference alternatives does not impact the probability of choosing the
530 indifference option. Within a quantum choice model framework, there are numerous possibilities
531 for capturing indifference. For the work on this dataset, we implement the simplest solution. This
532 is to assume that the indifference choice is a separate component of the belief state, using a 3-
533 dimensional Hilbert space. The indifferent alternative thus appears in the model equivalently to
534 any of the other alternatives, except that it does not depend directly on the attributes of the other

TABLE 4 : Observed shares of alternatives under each choice scenario in the couple commuter dataset.

| Scenario | Attribute changes | | | | Observed | | |
|----------|------------------------|------------|--------------------|----------------|----------|-------|-------------|
| | Travel time (TT, mins) | | Salary (SEK/month) | | SQ | NL | Indifferent |
| | Own TT | Own Salary | Partner TT | Partner Salary | | | |
| 1 | +10 | +500 | 0 | 0 | 70.3% | 24.5% | 5.2% |
| 2 | +25 | +500 | 0 | 0 | 70.0% | 23.9% | 6.1% |
| 3 | +10 | +1000 | 0 | 0 | 71.1% | 24.1% | 4.9% |
| 4 | +25 | +1000 | 0 | 0 | 69.5% | 25.3% | 5.2% |
| 5 | +10 | +500 | +10 | +500 | 74.4% | 20.6% | 5.0% |
| 6 | +10 | +500 | +25 | +500 | 73.6% | 21.2% | 5.2% |
| 7 | +10 | +500 | +10 | +1000 | 73.8% | 20.3% | 5.9% |
| 8 | +10 | +500 | +25 | +1000 | 76.0% | 19.2% | 4.7% |
| 9 | +25 | +500 | +10 | +500 | 74.4% | 21.3% | 4.3% |
| 10 | +25 | +500 | +10 | +1000 | 73.4% | 20.4% | 6.2% |
| 11 | +10 | +1000 | +10 | +500 | 74.8% | 20.6% | 4.6% |
| 12 | +10 | +1000 | +25 | +500 | 74.0% | 20.9% | 5.1% |
| 13 | +25 | +1000 | +10 | +500 | 72.4% | 22.5% | 5.1% |

535 alternatives, c.f. Eq. 3. It does however depend on the attributes indirectly, by the normalisation
536 of the components (see Eq. 4). However, by implementing the RRM value functions, our quantum
537 model inherits the property that choice probabilities will be invariant to uniform increases or
538 decreases of the attribute values. If, for example, we observe an increase of Δ_x across attribute x for
539 all alternatives, then there is no change in the amplitudes: $e^{\beta_k((x_{ntik}+\Delta_x)-(x_{ntjk}+\Delta_x))} = e^{\beta_k(x_{ntik}-x_{ntjk})}$.
540 This means that for the choice scenarios detailed in Table 4, the absolute values for a decision-
541 maker's travel time and salary do not have an impact: it is only the relative differences between the
542 status quo and new alternative that impact the choice probabilities, both in RRM and our quantum
543 amplitude model. This discussion explains the use of RRM as the base model against which we
544 compare our quantum model.

545 3.2.2. Basic models for the couple commuter dataset

546 For this dataset, there are two distinct choice sets: the first only includes factors impacting the
547 decision-maker alone (CT1) while the second additionally includes impacts on the partner (CT2).

548 For the QA model on the CT1 data, the amplitudes for the status quo (SQ), new location (NL)
549 and indifference (Ind) alternatives are then:

$$\Psi_{nt,SQ} = \frac{\delta_{base} + \delta_{SQ} + \ln(1 + e^{-\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{-\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}})}{\mathcal{N}_{nt}}, \quad (13)$$

550

$$\Psi_{nt,NL} = \frac{\delta_{base} + \ln(1 + e^{\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}})}{\mathcal{N}_{nt}}, \quad (14)$$

551 and

$$\Psi_{nt,Ind} = \frac{\delta_{Ind} + \delta_{base}}{\mathcal{N}_{nt}}. \quad (15)$$

552 We again estimate a constant that is added to the amplitude for all alternatives, δ_{base} , and \mathcal{N}_{nt} is
 553 a normalisation factor calculated using the numerators from each amplitude, Eqs. (13, 14, 15),
 554 in line with Eq. (4). For the remaining terms, we have that $\Delta_{O_{nt,TT}}$ is the change in the decision-
 555 maker's travel time, $\Delta_{O_{nt,Sal}}$ is the change in their salary and the β -coefficients estimate the relative
 556 importance of these attributes ('O' for 'own'). The amplitude for the new location alternative
 557 replaces $-\beta$ with β and obviously drops δ_{SQ} , where we do not show δ_{NL} , which is normalised
 558 to zero, while the constant δ_{Ind} is included for the indifference alternative.

559 For the random regret minimisation models, the random regret functions for the CT1 data are
 560 given by:

$$RR_{nt,SQ} = \delta_{SQ} + \ln(1 + e^{\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}}) + \varepsilon_{nt,SQ}, \quad (16)$$

$$RR_{nt,NL} = \delta_{NL} + \ln(1 + e^{-\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{-\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}}) + \varepsilon_{nt,NL}, \quad (17)$$

562 and

$$RR_{nt,Ind} = \delta_{Ind} + \varepsilon_{nt,Ind}. \quad (18)$$

563 Note that the direct comparison of the equations for amplitudes and regret allows for a clear
 564 mathematical interpretation of the difference between the models. Whereas the quantum models
 565 additionally have a normalisation factor such that the probabilities can be calculated directly from
 566 these amplitudes, using Eq. (2), the regret model implements uncertainty in which alternative is
 567 chosen through use of type I extreme value distributed error terms, ε . A further difference arises
 568 in that Δ_x and $-\Delta_x$ are interchanged when moving between amplitudes and regret. This is simply
 569 to ensure the correct sign for the directionality of the attributes in the respective models, with the
 570 negative of the regret used to calculate probabilities.

571 For CT2, additional terms are added for the attributes impacting the partner. An additional
 572 layer of flexibility is possible (and explored below), by allowing the parameters for own time and
 573 salary to be different in CT1 and CT2, i.e. not just allowing for differences between the evaluation
 574 of the impact on the respondent themselves (vs on the partner), but allowing that impact to be
 575 different when the impact on the partner is also considered.

576 The results of the basic quantum choice models together with the equivalent RRM models are
 577 given in Table 5. The first models (RRM-1 and QA-1) keep the parameters for the own salary and
 578 time constant between CT1 and CT2, labelling them as β_{OSal} and β_{OTT} . The second set (RRM-2
 579 and QA-2) have separate parameters for CT1 and CT2 for the own salary and cost, as well as
 580 separate constants for CT1 and CT2.

581 Regardless of whether RRM and QA are compared with or without separate parameters, the
 582 results indicate a substantial advantage for the quantum models. Additionally, both QA and RRM
 583 find clear evidence that the use of separate CT1 and CT2 parameters lead to further gains in fit,
 584 demonstrating that there is an inconsistency in how a decision-maker considers factors impacting
 585 themselves in the absence (CT1) or presence (CT2) of factors impacting their partner. These
 586 differences are clearly visible in the second set of models, where we see a reduction in both the
 587 own salary and own time parameters when going from CT1 to CT2, where this is an indication
 588 of differences in noise (lower parameters mean a less deterministic choice process), but also
 589 differences in relative valuations as the reduction is larger for the salary coefficient than for the
 590 time coefficient. The models imposing homogeneity between CT1 and CT2 are biased as a result
 591 and show that individuals attach higher values to their own salary and their own travel time, while
 592 the second set of models shows that this is only the case for salary.

TABLE 5 : Results of all basic models and models with quantum rotations for the couple commuter dataset, together with all parameter estimates.

| Type | | Basic Models | | | | Models with a quantum rotation | | | | | | | |
|---|--------------------------|--------------|------------|------------|------------|--------------------------------|------------|------------|------------|------------|------------|---------|---------|
| Specification | | RRM-1 | QA-1 | RRM-2 | QA-2 | QAR-2a | QAR-2b | QAR-2c | QAR-2d | QAR-2e | QAR-2f | | |
| Free parameters | | 6 | 7 | 10 | 12 | 11 | 11 | 11 | 11 | 11 | 11 | | |
| Log-likelihood | | -12,784.21 | -12,624.13 | -12,426.71 | -12,289.38 | -12,430.74 | -12,463.49 | -12,283.33 | -12,426.12 | -12,461.48 | -12,436.75 | | |
| Adj. ρ^2 | | 0.41908 | 0.42631 | 0.43514 | 0.44129 | 0.43491 | 0.43342 | 0.44161 | 0.43512 | 0.43351 | 0.43464 | | |
| BIC | | 25,612.62 | 25,299.83 | 24,927.10 | 24,667.17 | 24,942.52 | 25,008.01 | 24,647.70 | 24,933.28 | 25,004.00 | 24,954.55 | | |
| Average probability of chosen alternative (by type of alternative and by experiment) | | | | | | | | | | | | | |
| CT1 | Status Quo | 77.66% | 75.61% | 76.97% | 77.73% | 77.84% | 77.74% | 77.63% | 77.90% | 77.70% | 78.07% | | |
| | New Location | 44.47% | 40.97% | 42.39% | 43.10% | 44.04% | 44.00% | 43.04% | 44.24% | 44.22% | 43.97% | | |
| | Indifferent | 1.91% | 9.28% | 5.01% | 6.22% | 6.76% | 6.76% | 6.24% | 6.60% | 6.67% | 6.70% | | |
| CT2 | Status Quo | 76.62% | 78.70% | 77.86% | 78.19% | 77.44% | 77.75% | 78.23% | 77.62% | 77.93% | 77.07% | | |
| | New Location | 29.38% | 29.41% | 33.47% | 33.54% | 28.78% | 27.73% | 34.08% | 28.40% | 27.57% | 28.72% | | |
| | Indifferent | 8.04% | 3.54% | 5.00% | 5.37% | 5.22% | 5.29% | 5.25% | 5.35% | 5.26% | 5.35% | | |
| Overall | | 64.38% | 64.18% | 64.84% | 65.35% | 64.69% | 64.66% | 65.39% | 64.76% | 64.72% | 64.61% | | |
| Parameter Estimates | | | | | | | | | | | | | |
| Choice Set | | both | both | CT1 | CT2 | CT1 | CT2 | both | both | both | both | both | |
| β_{ORT} | est. | -0.1434 | -3.0200 | -0.1609 | -0.1290 | -0.0747 | -0.0315 | -0.1875 | -0.1554 | -0.0692 | -0.1617 | -0.1445 | -0.1960 |
| | rob.t-rat. | -39.89 | -16.95 | -37.19 | -30.43 | -7.16 | -13.04 | -8.80 | -10.91 | -9.96 | -10.33 | -11.63 | -6.79 |
| β_{OSal} | est. | 2.1004 | 26.3856 | 2.4834 | 1.4860 | 0.9225 | 0.3381 | 1.8225 | 1.6141 | 0.8541 | 1.6326 | 1.5364 | 1.8534 |
| | rob.t-rat. | 35.69 | 17.99 | 31.93 | 15.80 | 9.18 | 6.95 | 11.38 | 13.77 | 11.80 | 13.55 | 14.72 | 9.05 |
| β_{PRT} | est. | -0.0956 | -1.5624 | | -0.1315 | | -0.0332 | -0.1580 | -0.1370 | -0.0754 | -0.1381 | -0.1234 | -0.1773 |
| | rob.t-rat. | -35.77 | -26.04 | | -28.78 | | -14.74 | -13.88 | -17.37 | -15.31 | -15.74 | -17.57 | -10.46 |
| β_{PSal} | est. | 1.3103 | 15.1615 | | 0.8569 | | 0.2052 | 1.7746 | 1.5900 | 0.5142 | 1.6317 | 1.6599 | 1.5995 |
| | rob.t-rat. | 21.77 | 35.19 | | 5.40 | | 3.74 | 8.42 | 8.79 | 4.67 | 10.41 | 9.56 | 7.37 |
| δ_{SQ} | est. | -0.3498 | -8.7204 | -0.5274 | 0.8100 | 0.0056 | -0.2434 | -0.4447 | -0.2817 | 0.0055 | -0.3365 | -0.2380 | -0.5032 |
| | rob.t-rat. | -5.43 | -8.03 | -6.88 | 4.33 | 0.15 | -7.28 | -4.03 | -3.78 | 0.20 | -4.02 | -3.60 | -3.44 |
| δ_{IND} | est. | 5.1402 | 10.2110 | 4.2313 | 6.1702 | 1.1199 | 2.4040 | 1.1086 | 1.1086 | 1.1221 | 1.0972 | 1.1075 | 1.1066 |
| | rob.t-rat. | 64.77 | 12.01 | 50.96 | 52.16 | 45.65 | 352.05 | 35.11 | 40.10 | 55.29 | 39.97 | 42.23 | 33.92 |
| δ_{base} | est. | | 1.2753 | | | | -0.8342 | -0.5590 | -0.6243 | -0.8522 | -0.6151 | -0.6524 | -0.5510 |
| | rob.t-rat. | | 2.06 | | | | -16.93 | -221.78 | -11.29 | -15.27 | -23.14 | -14.55 | -17.10 |
| First Rotation | | | | | | | | 1-2 | 1-2 | 1-3 | 1-3 | 2-3 | 2-3 |
| Second Rotation | | | | | | | | 1-3 | 2-3 | 1-2 | 2-3 | 1-3 | 1-2 |
| ω_{1-2} | est. | | | | | | | 1.3914 | 1.0363 | 0.8699 | | 1.3074 | |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | -3.34 | -0.79 | -15.70 | | -2.05 | |
| ϑ_{1-2} | est. | | | | | | | 2.8047 | 3.0650 | 1.9568 | | 0.2188 | |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | 44.56 | 23.58 | 9.33 | | -26.57 | |
| ω_{1-3} | est. | | | | | | | 0.3423 | | 1.6702 | 2.7346 | | 1.3994 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | 13.75 | | 7.19 | 2.86 | | -9.03 |
| ϑ_{1-3} | est. | | | | | | | 0.5017 | | 1.6371 | 2.8437 | | 0.8244 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | -22.57 | | 0.74 | 28.91 | | -5.16 |
| ω_{2-3} | est. | | | | | | | | 1.2713 | | 1.2225 | 0.5071 | 1.6737 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | | -16.68 | | -16.78 | -20.56 | 2.03 |
| ϑ_{2-3} | est. | | | | | | | | 1.4465 | | 1.5556 | 2.8602 | 1.2224 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | | | -2.13 | | -0.46 | 108.97 | -0.75 |

593 *3.2.3. Models with quantum rotations for the couple commuter dataset.*

594 This dataset also provides opportunities for the use of additional features from quantum choice
 595 models to test for an inconsistency or ‘change of perspective’ incurred through changing from
 596 thinking about just yourself compared to yourself and your partner. We test the change of perspective
 597 to the choice task with attributes impacting the partner through two consecutive quantum rotations
 598 over the alternatives (status quo, new policy and indifferent). For our models implementing
 599 quantum rotations, we use Eqs. (13, 14, 15) to define the amplitudes for the alternatives within the
 600 first set of choice tasks. For the amplitudes under the second set of choice tasks, we initially use
 601 these equations to estimate the amplitudes before then applying quantum rotations. Thus, for these
 602 models, we estimate a single set of coefficients that apply to choices made in both choice sets. We
 603 then require a product of two rotation matrices for adjusting the amplitudes appropriately when
 604 additionally considering travel time and salary changes for the partner. The new amplitudes after
 605 the rotation are then given by:

$$\Psi_f = R_B R_A \Psi_{0,}, \quad (19)$$

606 where R_A and R_B are both estimated using Eq. (6) and rotation matrices based on R_2 with the
 607 use of axis and angle parameters. We again find that fixing $n_x = 0$ results in no loss of model fit,
 608 leaving us with four free parameters, ω_A , ω_B , ϑ_A and ϑ_B , where we again set $n_y = \cos(\omega)$ and
 609 $n_z = \sin(\omega)$. Given that we implement two consecutive rotations on pairs of alternatives, there are
 610 six combinations of pairwise rotations. The results of these six models are given in Table 5. In
 611 all six cases, we see an improvement in fit over the basic model (QA-1). The third option (QAR-
 612 2c) which first rotates between the status quo and the indifference option (alternatives 1 and 3),
 613 before rotating between the status quo and the new option (alternatives 1 and 2), offers the most
 614 substantial improvement in fit. It also outperforms the second basic model (QA-2), suggesting that
 615 the rotations can better account for the differences between tasks completed in the different choice
 616 sets than is the case for using separate parameters.

617 *3.2.4. Models with complex phases for the couple commuter dataset*

618 We next turn to the incorporation of complex phases, where we again test a number of possible
 619 specifications, given that there are six different attributes and many possibilities for how many
 620 phases to implement. We consider the following possibilities for how to introduce complex phases.

- 621 1. A model with a single complex phase, φ , that is applied to all of the attributes.
- 622 2. A model with two complex phases, φ_1 and φ_2 , with the first applied to attributes impacting
623 the decision-maker and the second applied to attributes impacting the partner
- 624 3. A model with two complex phases, with the first applied to travel time attributes and the
625 second applied to salaries
- 626 4. A model with two complex phases, with the first applied to attributes in the first set of choice
627 tasks, and the second applied to attributes in the second set of choice tasks
- 628 5. A model with six complex phases with six free parameters, $\{\varphi_1, \dots, \varphi_6\}$, with a different
629 phase for each attribute in each set of choice tasks.

TABLE 6 : Results of all models with complex phases and the combined models for the couple commuter dataset, together with all parameter estimates, where \circ and \star indicate attribute pairs which have the same phase.

| Type | | Models with complex phases | | | | | Combined | |
|---|--------------------------|----------------------------|------------------|-----------------|--------------------|------------|-------------------|------------------|
| Specification | | QAPh-1 | QAPh-2 | QAPh-3 | QAPh-4 | QAPh-5 | QAC-1 | QAC-2 |
| Free parameters | | 8 | 9 | 9 | 9 | 13 | 17 | 15 |
| Log-likelihood | | -12,536.66 | -12,366.51 | -12,536.65 | -12,487.07 | -12,319.10 | -12,249.70 | -12,250.21 |
| Adj. ρ^2 | | 0.43024 | 0.43792 | 0.43019 | 0.43244 | 0.43989 | 0.44286 | 0.44293 |
| BIC | | 25,132.26 | 24,799.33 | 25,139.60 | 25,040.45 | 24,733.98 | 24,624.65 | 24,610.94 |
| Average probability of chosen alternative (by type of alternative and by experiment) | | | | | | | | |
| CT1 | Status Quo | 75.57% | 76.99% | 75.57% | 76.21% | 77.79% | 78.15% | 78.18% |
| | New Location | 39.84% | 42.51% | 39.84% | 39.36% | 42.96% | 43.92% | 43.84% |
| | Indifferent | 8.77% | 6.83% | 8.76% | 8.34% | 6.65% | 6.13% | 6.15% |
| CT2 | Status Quo | 79.57% | 78.57% | 79.58% | 78.99% | 78.32% | 78.21% | 78.22% |
| | New Location | 33.13% | 31.82% | 33.13% | 33.51% | 32.81% | 34.15% | 34.13% |
| | Indifferent | 4.01% | 5.40% | 4.01% | 4.37% | 5.40% | 5.26% | 5.27% |
| Overall | | 64.79% | 65.02% | 64.79% | 64.76% | 65.34% | 65.65% | 65.66% |
| Parameter Estimates | | | | | | | | |
| β_{TT} | est. | -3.1325 | -0.1441 | -3.1557 | -3.3643 | -0.0709 | -0.0385 | -0.0383 |
| | rob.t-rat. | -12.99 | -28.52 | -8.63 | -14.15 | -18.58 | -9.75 | -9.96 |
| β_{Sal} | est. | 17.9584 | 1.4095 | 18.0740 | 26.0038 | 0.8198 | 0.6026 | 0.5430 |
| | rob.t-rat. | 13.83 | 22.79 | 8.92 | 14.09 | 17.04 | 7.28 | 11.10 |
| β_{PTT} | est. | -2.0343 | -0.0992 | -2.0487 | -2.6486 | -0.0908 | -0.0513 | -0.0543 |
| | rob.t-rat. | -14.07 | -18.67 | -8.96 | -14.95 | -10.33 | -7.12 | -9.03 |
| β_{PSal} | est. | 9.0215 | 0.6876 | 9.0752 | 10.1627 | 0.5504 | 0.2528 | 0.2530 |
| | rob.t-rat. | 1.20 | 7.43 | 8.38 | 18.89 | 6.44 | 5.07 | 5.00 |
| δ_{SQ} | est. | -41.2320 | -0.5687 | -41.4785 | -33.3201 | -0.0046 | 0.0992 | 0.0784 |
| | rob.t-rat. | -12.40 | -6.16 | -8.57 | -11.00 | -0.15 | 4.85 | 5.04 |
| δ_{IND} | est. | 6.6360 | 1.2861 | 6.7424 | 8.9254 | 0.7372 | 1.0810 | 1.0512 |
| | rob.t-rat. | 10.09 | 36.59 | 7.70 | 10.35 | 15.23 | 81.06 | 32.53 |
| δ_{base} | est. | 1.1958 | -0.8424 | 1.1482 | 0.7655 | -0.9828 | -1.2130 | -1.1817 |
| | rob.t-rat. | 2.59 | -25.32 | 2.75 | 17.27 | -27.24 | -99.16 | -55.73 |
| ω_{1-2} | est. | | | | | | 0.7219 | 0.3527 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | -7.57 | -9.96 |
| ϑ_{1-2} | est. | | | | | | 2.3048 | 2.5050 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | 5.86 | 18.47 |
| ω_{1-3} | est. | | | | | | 1.6817 | 1.7523 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | 3.55 | 3.94 |
| ϑ_{1-3} | est. | | | | | | 2.3981 | 2.7212 |
| | rob.t-rat. (vs $\pi/2$) | | | | | | 3.49 | 9.95 |
| φ_{OTT_1} | est. | 0.3958 $^\circ$ | 0.5282 $^\circ$ | 0.3960 $^\circ$ | 0.7655 $^\circ$ | 0.1119 | 0.1653 | 0.0619 $^\circ$ |
| | rob.t-rat. | 17.62 | 31.39 | 17.60 | 17.27 | 2.12 | 2.55 | 1.76 |
| φ_{OTT_2} | est. | 0.3958 $^\circ$ | 0.5282 $^\circ$ | 0.3958 $^\circ$ | -3.04E-06 * | -1.0690 | 0.2035 | 0.0619 $^\circ$ |
| | rob.t-rat. | 17.62 | 31.39 | 17.60 | -4.13 | -15.75 | 1.41 | 1.76 |
| φ_{PTT} | est. | 0.3958 $^\circ$ | -1.2984 * | 0.3958 $^\circ$ | -3.04E-06 * | 1.2073 | 0.3628 | 0.2338 |
| | rob.t-rat. | 17.62 | -29.61 | 17.60 | -4.13 | 25.92 | 2.69 | 3.78 |
| φ_{Sal_1} | est. | 0.3958 $^\circ$ | 0.5282 $^\circ$ | 0.1602 * | 0.7655 $^\circ$ | 0.2671 | 0.1045 | 0.1502 * |
| | rob.t-rat. | 17.62 | 31.39 | 0.41 | 17.27 | 11.21 | 4.69 | 6.75 |
| φ_{Sal_2} | est. | 0.3958 $^\circ$ | 0.5282 $^\circ$ | 0.1602 * | -3.04E-06 * | 0.7928 | 0.5541 | 0.1502 * |
| | rob.t-rat. | 17.62 | 31.39 | 0.41 | -4.13 | 12.23 | 3.77 | 6.75 |
| φ_{PSal} | est. | 0.3958 $^\circ$ | -1.2984 * | 0.1602 * | -3.04E-06 * | -1.0220 | -0.5316 | -0.7645 |
| | rob.t-rat. | 17.62 | -29.61 | 0.41 | -4.13 | -27.09 | -2.99 | -3.29 |

630 The results of these different possibilities are given in Table 6. The incorporation of a larger
 631 number of complex phases opens up the potential for large gains in fit, but the actual specification

632 of the phases is important. For example, a significant gain is found by moving from a single
 633 phase to two phases for each combination except for the model with different phases for travel
 634 time as opposed to salaries (QAPh-3). The most substantial of these gains is found by QAPh-2,
 635 which has separate phases for attributes impacting the decision-maker and attributes impacting
 636 their partner. The best performing model overall is a model with a different phase for each of
 637 the different attributes, suggesting that, as with the first dataset, the attributes are considered
 638 differently. However, this model does not perform as well as a basic quantum amplitude model
 639 with separate parameters for the different choice sets (see Table 5). Consequently, as opposed to
 640 the results of the first dataset, it is the addition of quantum rotations rather than complex phases
 641 that better captures the implicit change in choice context.

642 3.2.5. Combined model for the couple commuter dataset

643 For our combined model, we again utilise a model with both quantum rotations and complex
 644 phases to capture the change of perspective when commute attributes concerning the partner are
 645 present. Given the good performance of QAPh-5, which has six phases, and of QAR-2c, we opt
 646 to combine these models for our final model. This means that it has 7 parameters in common with
 647 the basic model (QA-1), 6 complex phases (with one for each attribute) and 4 rotation parameters,
 648 as before for the models with quantum rotations. Note that we implement rotations based on the
 649 best performing rotation model, thus first rotating between the status quo and the indifference
 650 option (axis parameter ω_{13} , angle ϑ_{13}) before rotating between the status quo and the new policy
 651 alternative (axis parameter ω_{12} , angle ϑ_{12}).

652 Table 6 gives the results of our combined model. This time, in contrast with the results for the
 653 taboo trade-off dataset, we see that the model (QAC-1) combining quantum rotations and complex
 654 phases does offer a significant improvement over a model offering only one of these additional
 655 features to capture the change of perspective. We also see that the model with six phases has
 656 rather different estimates for the phases for the same attributes across the different choice sets,
 657 suggesting that these attributes cannot be treated equivalently (Fig. 3). For the combined models,
 658 we find significant estimates for both the phase and rotation parameters. However, we note that
 659 there is not a significant difference between the phase parameters across choice sets ($\varphi_{O_{Sal_1}}$ and
 660 $\varphi_{O_{Sal_2}}$) and (φ_{OTT_1} and φ_{OTT_2}). It thus appears that the quantum rotation, which is used for the
 661 ‘change of perspective’ from the first choice task to the second choice task, already captures the
 662 difference between choice sets. We consequently include a second combined model (QAC-2) with
 663 just four complex phases. This final model does not result in a significant loss of model fit, as
 664 expected, and achieves the best adj. ρ^2 and BIC.

665 This effect is particularly clear through a closer consideration of the estimates for the complex
 666 phase parameters, φ . These are displayed graphically in Figure 3. For the model with complex
 667 phases only (QAPh-5), we observe very different estimates across attributes, choice task set and
 668 whether an attribute affects the decision-maker or the partner. This illustrates why the QAPh-5
 669 model can outperform the models with only two complex phases, with the flexibility of interactions
 670 across all attributes clearly helping to improve performance. The addition of quantum rotations,
 671 (moving from QAPh-5 to QAC-1) results in phases regressing closer to smaller values (modulo
 672 2π). This results in a weaker interference interaction across the attributes, with the real parts
 673 growing in magnitude whilst the imaginary parts shrink. The only exception is the phase to attribute
 674 OTT-2 which appears to vary strongly. However, the phase to OTT-2 in QAC-1 is not reliable (t-
 675 value = 1.41), hence its value shift from QAPh-5 to QAC-1 should not necessarily be understood

676 as a significant adaptation but rather a shift from a spurious local optimisation value in QAC-1.
 677 Notably, the estimates for OTT-1 and OTT-2 are similar in QAC-1, and the use of only one phase
 678 for the decision-maker’s travel times (and one phase for salary) gives us the result in QAC-2, which
 679 records an insignificant loss of model fit.

680 Table 6 also compares the average probability for the chosen alternative under each of these
 681 models. The combined models do better than other models for choices where the decision-maker
 682 opts to change to the new policy, with the combination of quantum rotations and complex phases
 683 evidently helping capture these choices. The coefficients associated with attributes (β) change
 684 substantially across the different models, with the ratios of parameters also changing. A decision-
 685 maker’s own salary ranges from being approximately equivalently as important as their partner’s
 686 salary, to more than double the importance in the combined model. The converse is true for travel
 687 times, with the combined model indicating a partner’s travel time is of greater importance than that
 688 of the decision-maker. The opposite is true in the basic model.

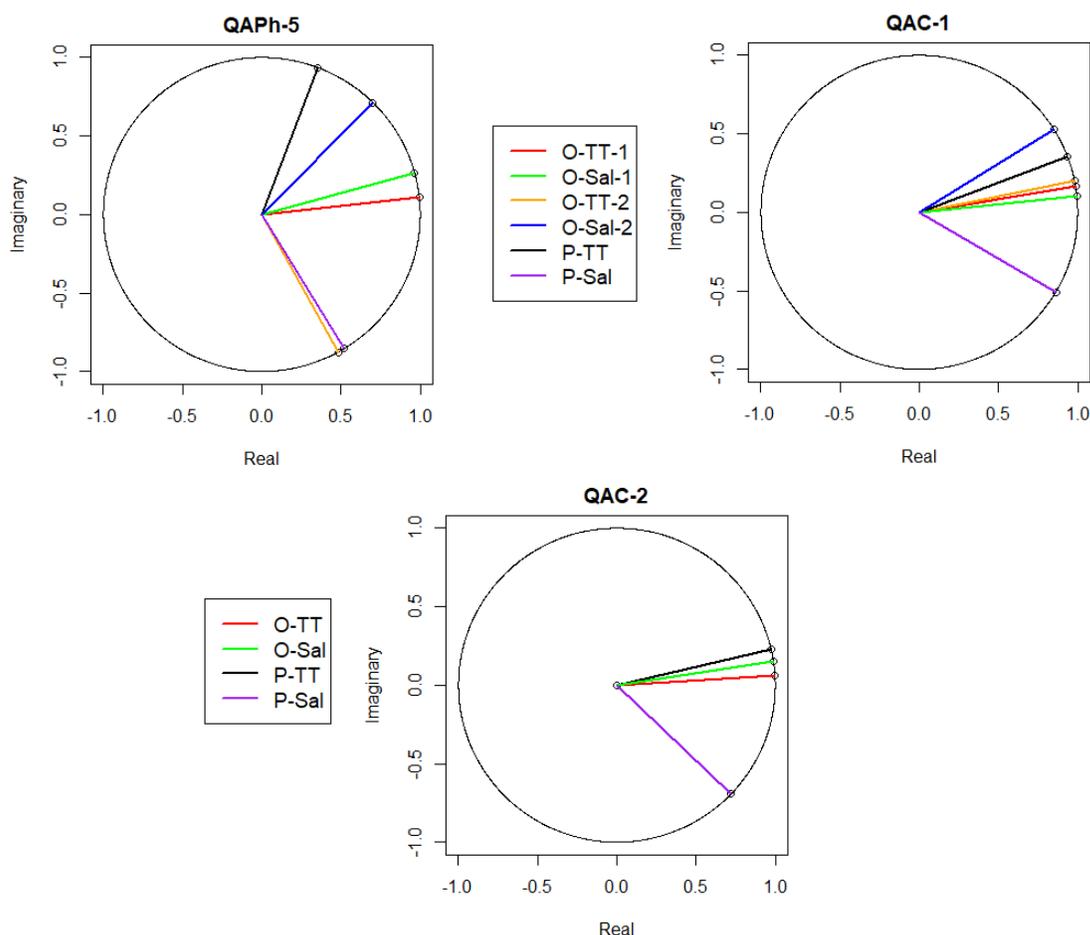


FIGURE 3 : Illustration of the estimated complex phase coefficients for the travel time (TT), salary increase (Sal) of the choice maker (O) and partner (P) in the quantum models QAPh-5 (only complex phases), QAC-1 (rotations and 6 phases) and QAC-2 (rotations and 4 phases). Model QAC-2 keeps the same phases for the choice set CT1 (self) and CT2 (self and partner).

689 4. CONCLUSIONS

690 The growing interest in moral decision-making in choice modelling calls for the development of
691 appropriate model specifications. The present paper has focussed on quantum probability and
692 demonstrated that quantum rotations as well as complex phases accurately capture an implicit
693 change in decision context when a more salient moral element enters the dimension of choice.

694 For our first choice paradigm with a ‘Taboo trade-off’, we find that models containing a
695 perspective operation implemented by both rotations and complex phases do not significantly
696 improve upon models with just one of these features. This however is not the case for the second
697 choice paradigm with a moral component due to choices impacting the partner, in which our
698 combined model with a perspective operation that has both features outperforms simpler specifications.
699 Further work is thus required to establish the relative strengths and merits of these different features
700 for the choice maker’s implicit perspective change, with it being possible that the first choice
701 scenario is too simple (in having only two alternatives) to merit further model features. Importantly,
702 quantum models have the potential to offer better performance than more conventional approaches
703 in both datasets, as shown by our empirical results.

704 Overall, whilst the results for the quantum choice models in this paper are promising, it is not
705 clear that they are distinctly *better* than those of [Hancock et al. \(2020\)](#). This implies that we cannot
706 necessarily attribute the success of the quantum rotations and complex phases to the fact that there
707 are moral components in the choices modelled. This is particularly clear from the result that our
708 quantum model already has better model fit than the random regret model for the second dataset
709 tested in this paper *before* the moral component was captured through the additional quantum
710 model features. Further tests of quantum probability theory based models could shed light on
711 whether they are models that are particularly suited to moral decision-making with salient attribute
712 scenarios, or whether they are suitable for decision-making in general.

713 Further models should consider different sorts of moral choice data and scenarios. For example,
714 quantum models may be well suited for modelling choices made in ‘moral machine’ choice tasks.
715 The application of these models to choice scenarios where multiple individuals disagree, communicate
716 and reassess on what is their ‘most ethical’ choice would be particularly interesting. On such
717 socially sensitive matters moreover, results may also differ significantly for *revealed* preference
718 datasets due to continuing concerns about external validity of *stated* moral choices ([Bauman et al.,](#)
719 [2014](#)).

720 Closer to our present study, given that quantum models explicitly assume that a decision-
721 maker is uncertain about their choice, an ‘indifferent’ (or equivalently a ‘neither’) alternative may
722 be better modelled not as a separate alternative, but based on the superposition principle. The
723 indifferent belief state would be expressed through a superposition of the belief states for each of
724 the two choices. Such a superposition could contain a relative complex phase, which could depend
725 on specific attributes of the alternatives. Such an approach would then resort to an interference
726 effect between the belief states supporting the respective choices. The representation space would
727 be smaller again - a 2-dimensional Hilbert space, and its choice probabilities renormalised to
728 include the third - indifference - option. Other extensions to explore scenarios with an indifference
729 option could make the indifference-component of the belief state explicitly dependent on the
730 attributes of the choices (as a contrast to Eq. 15). Such a function could, for example, express an
731 additional effect at play in the balance of the two other choices; the indifference between two very
732 favourable choices may be less prominent than the indifference between two pale choices - due to
733 a lack of interest. A further theoretical development of the quantum model could incorporate the

734 impact of previous choices through a carry-over parameter that modifies the amplitude of present
735 quantum perspective operation. Finally, another next step could be to test the choice-maker for
736 explicit ethical answerability of the choice alternatives first. For example, in the taboo trade-
737 off paradigm, a decision-maker's explicit change of perspective could then be further analysed
738 from the tensorial belief state (Status Quo, New Policy, Indifferent) \otimes (Ethical, Not-Ethical), and
739 compared to a test where only an *implicit* change of perspective is assumed.

740 Whilst we include a discussion on various parameter ratios, one clear weakness of the new
741 quantum choice models developed here is that, by not being grounded in microeconomic theory,
742 they cannot be used to compute context independent welfare measures. This is a common limitation
743 of all models that included departures from a random utility framework. With our previous work
744 (Hancock et al., 2020) demonstrating that quantum choice models can produce forecasts and
745 elasticities, further research is needed to establish how the outputs can be used in an appraisal
746 context.

747 Overall, however, our results indicate that choice models with a quantum probability framework
748 have vast potential, both within moral choice scenarios and more generally.

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